MAVLINK to Timezero Server

The **MAVLINK to TimeZero Server** is a dedicated computer that converts MAVLINK protocol data into **NMEA0183** protocol, allowing it to be displayed on **TimeZero** software.

Getting Started

Powering On the System

The software comes pre-installed on a Lenovo computer. To start the system:

1. **Plug in the power** and turn on the Lenovo computer by pressing the front **power button**.

Network Setup

- The computer uses **DHCP** to obtain an IP address automatically.
- Connect an Ethernet cable from the Lenovo computer to a router.
- Once connected, the computer will receive an IP address dynamically.

Finding the Computer's IP Address

To locate the IP address of the Lenovo computer on your network:

- 1. Download and install Advanced IP Scanner: https://www.advanced-ip-scanner.com/
- 2. Run the software to scan your local network and find the Lenovo computer's IP address.

Accessing the Web Interface

Once you have the IP address, open a **web browser** (Google Chrome, Firefox, etc.) and enter:

http://LENOVO_COMPUTER_IP:8080

(Replace LENOVO_COMPUTER_IP with the actual IP address you found in the previous step.)

This web interface allows you to monitor connected drones in real time.

Drone Server Live Drone States				
Drone 1	Drone 2	Drone 3	Drone 4	Drone 5
Position Loading	Position Loading	Position Loading	Position Loading	Position Loading
Battery Status Loading	Battery Status Loading	Battery Status Loading	Battery Status Loading	Battery Status Loading
Speed & Throttle Loading	Speed & Throttle Loading	Speed & Throttle Loading	Speed & Throttle Loading	Speed & Throttle Loading
Energy Consumed Loading	Energy Consumed Loading	Energy Consumed Loading	Energy Consumed Loading	Energy Consumed Loading
Refresh	Refresh	Refresh	Refresh	Refresh
Download CSV	Download CSV	Download CSV	Download CSV	Download CSV
Start New CSV	Start New CSV	Start New CSV	Start New CSV	Start New CSV
Drone CSV Data				
Drone ID Time File				
All CSVs				

MAVLINK to NMEA0183 Data Conversion

MAVLINK Input

The server listens for MAVLINK data via UDP packets on the following ports:

- $14551 \rightarrow \text{Drone } 1$
- $14552 \rightarrow \text{Drone } 2$
- **14553** → Drone 3
- $14554 \rightarrow \text{Drone } 4$
- $14555 \rightarrow \text{Drone } 5$

NMEA0183 Output

The server provides NMEA0183 data via TCP streams on these ports:

- 5001 \rightarrow Drone 1
- $5002 \rightarrow \text{Drone } 2$
- 5003 \rightarrow Drone 3
- 5004 \rightarrow Drone 4
- $5005 \rightarrow \text{Drone } 5$

For people using an Herelink with QGC, use the Mavlink forwarding feature : <u>https://docs.qgroundcontrol.com/master/en/qgc-user-guide/settings_view/mavlink.html#grou_nd_station</u> to send the Mavlink data to the Levono address. URL to set beeing : LENOVO_COMPUTER_IP:14551 for drone1 . Adjust according to the drone number.

Connecting to TimeZero

To configure **TimeZero** to receive NMEA data from the server, follow the **official TimeZero manual**:

S TimeZero User Guide

Use the **Connection Assistant** in TimeZero to establish a TCP connection to the **NMEA0183 stream** you need.

HereLink WiFi Configuration

To simplify HereLink WiFi connections, a 5GHz WiFi router is provided.

Setting Up the Router

- 1. **Power on the router**.
- 2. Connect an Ethernet cable from the router's blue (WAN) port to your main router.
- 3. The router will create a WiFi network named herelink20.
- 4. The WiFi password is:

herelink20

Now, HereLink devices can connect to this network for seamless communication.